

Generative Modeling with Succinct Representation Learning via Wyner's Common Information

Jongha (Jon) Ryu
MIT

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Alice was beginning to get very tired of sitting ...when suddenly a White Rabbit with pink eyes ran close by her ...see it pop down a large rabbit-hole under the hedge.



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the bird has a white body,
black wings, and webbed
orange feet



a blue bird with gray
primaries and secondaries
and white breast and throat

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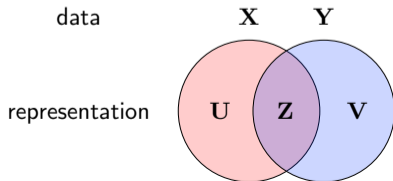
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 - **Cross-domain retrieval:** Given a query \mathbf{x} , retrieve relevant \mathbf{y} 's from a pool $\{\mathbf{y}_i\}_{i=1}^n$

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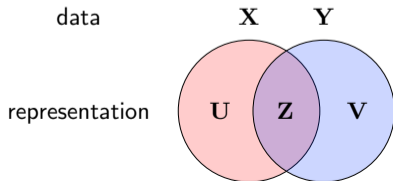
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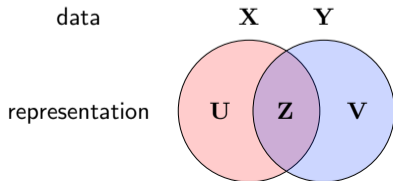
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 - a.k.a. cross-domain disentanglement problem



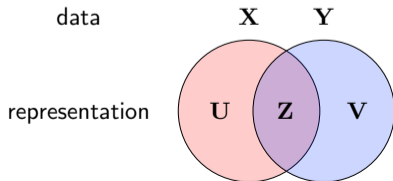
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- **Proposal:** use **Wyner's common information** to learn **succinct common representation**



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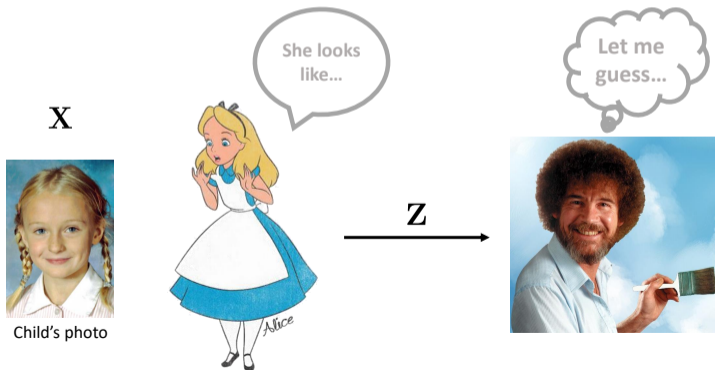


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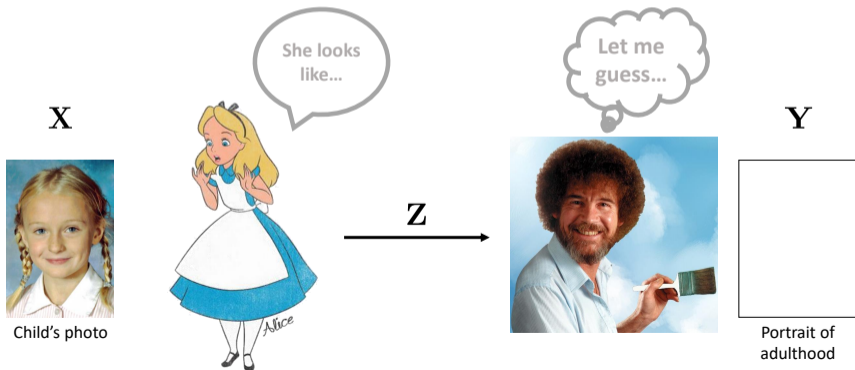
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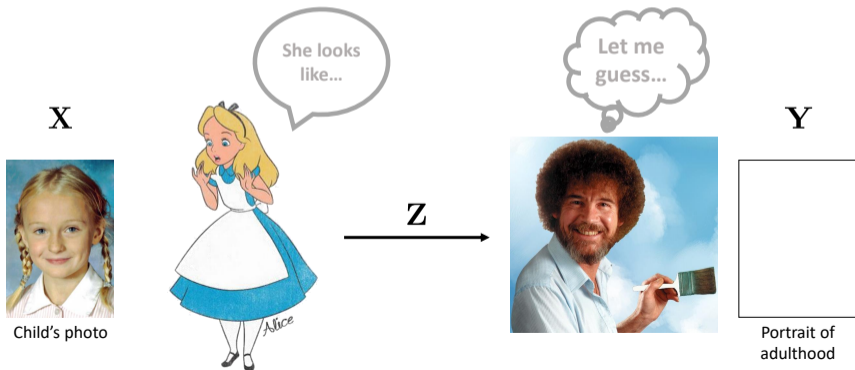
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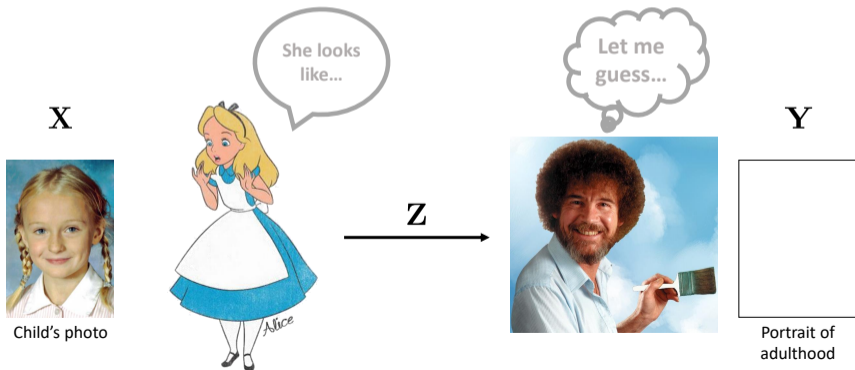
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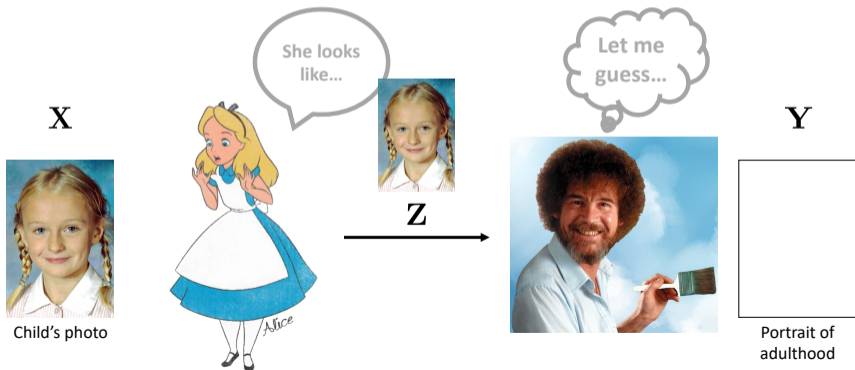
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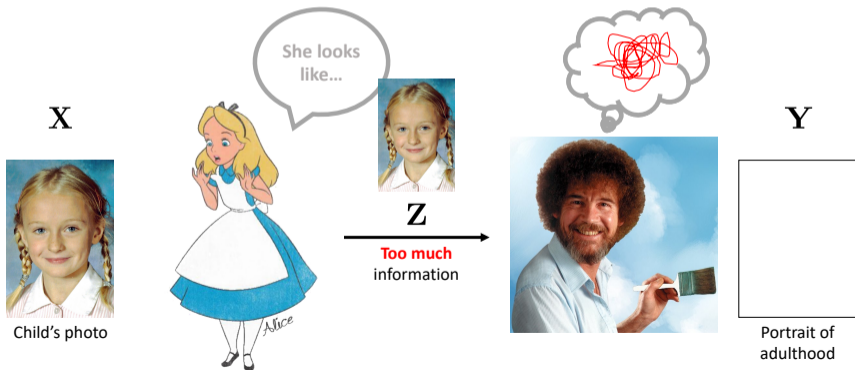
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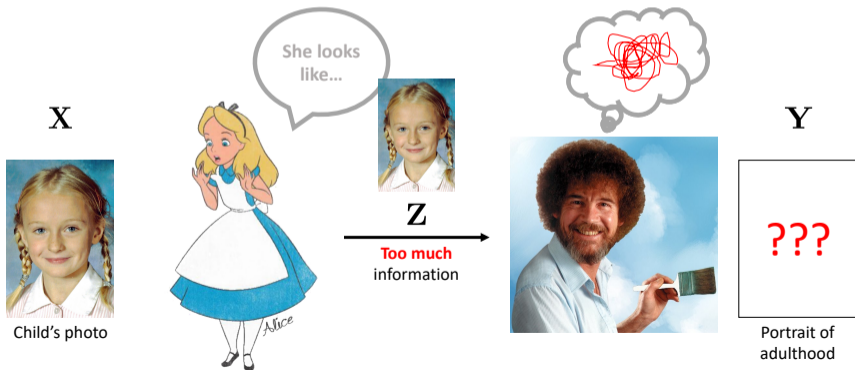
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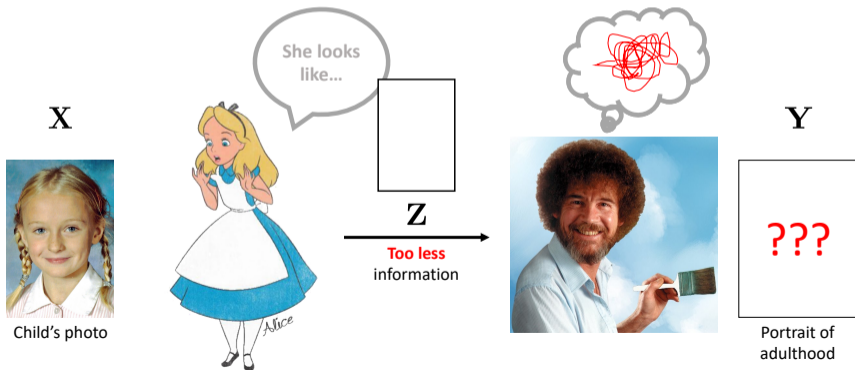
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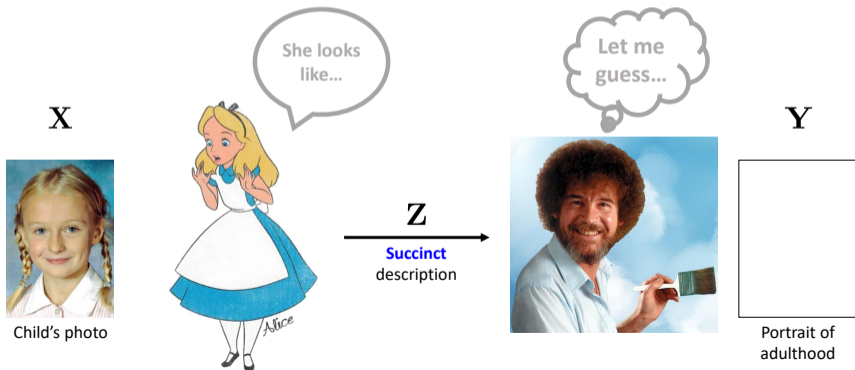
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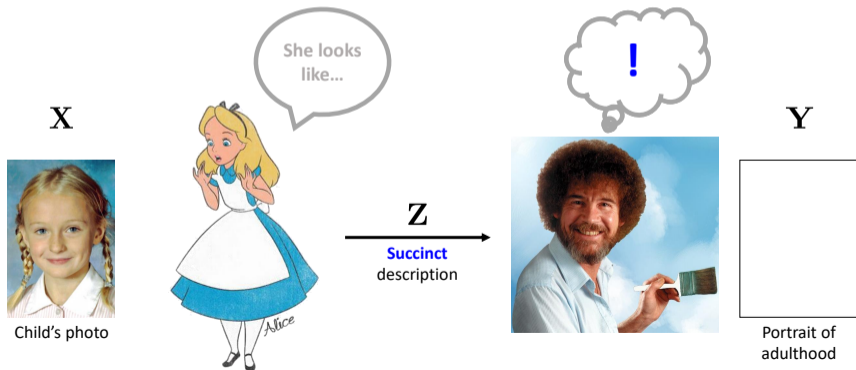
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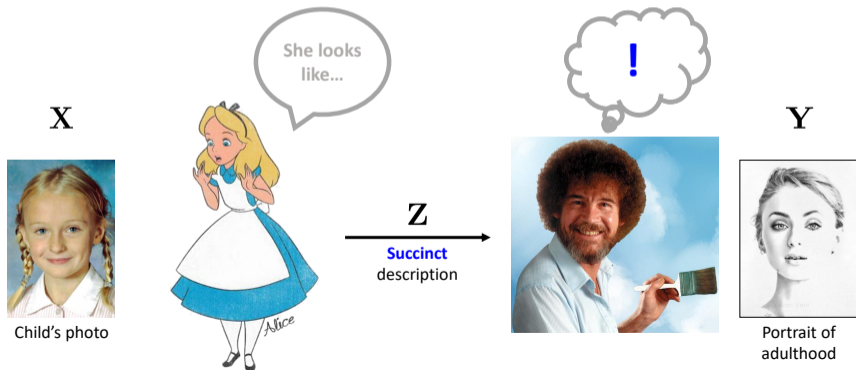
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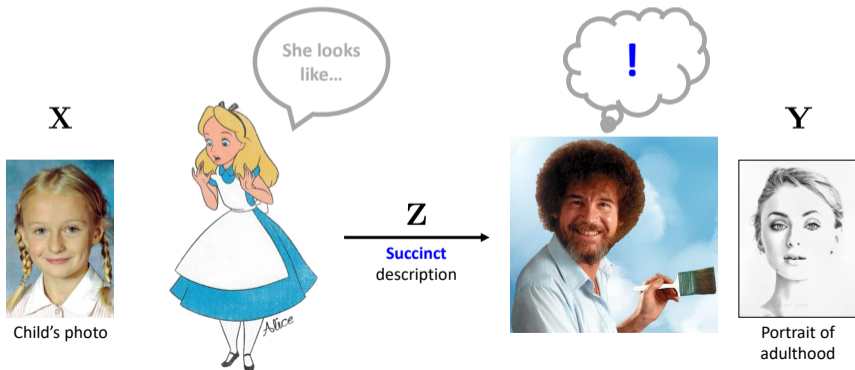
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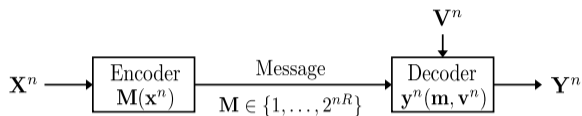
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- **Alice** can **maximally** help **Bob** by providing the most “**succinct**” description!



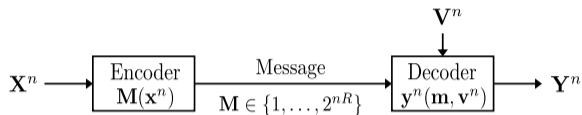
Channel synthesis (Cuff 2013)

- **Problem:** simulate a channel $q(\mathbf{y}|\mathbf{x})$ by communicating nR bits



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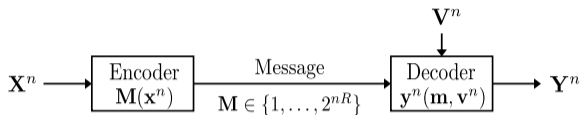
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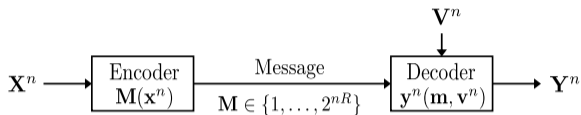


- **Question:** What is the minimum rate R^* ?
- **Answer:** Wyner's common information $R^* = J(\mathbf{X}; \mathbf{Y})$

minimize	$I(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$\mathbf{X} - \mathbf{Z} - \mathbf{Y}$
variables	$q(\mathbf{z} \mathbf{x}, \mathbf{y})$

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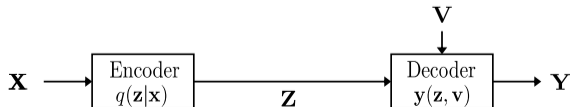
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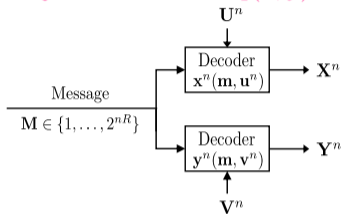
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- Single-letter characterization



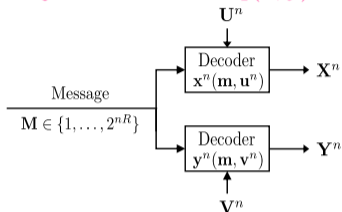
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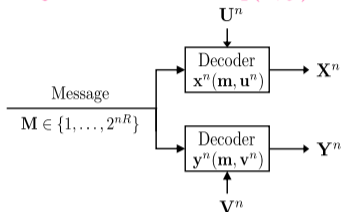
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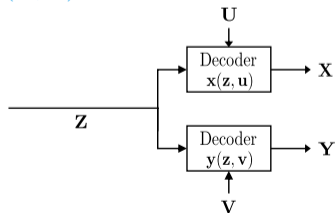
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Learning distributions based on Wyner's common information

- Channel synthesis \rightarrow conditional generation
- Distributed simulation \rightarrow joint generation
- Joint and conditional distributions share the same common information structure

minimize	$I(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
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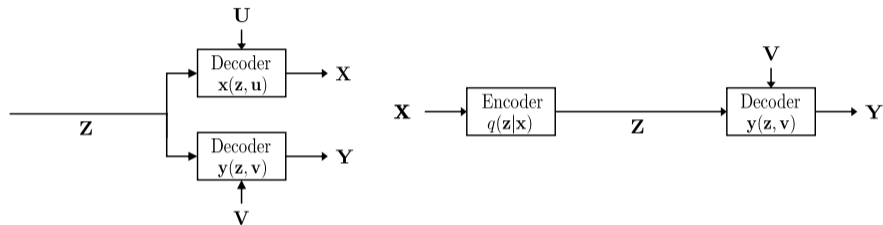
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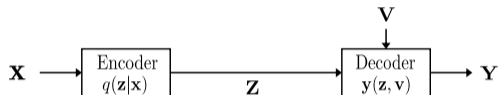
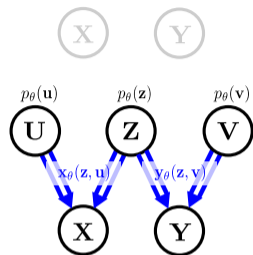
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- We will fit the generative models to data based on Wyner's optimization problem

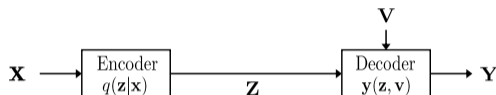
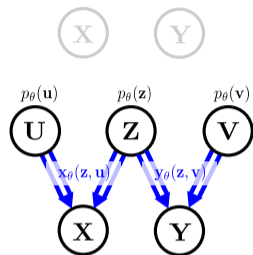
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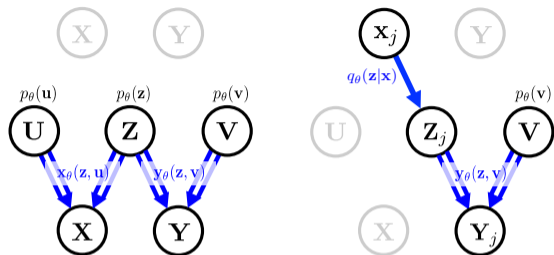


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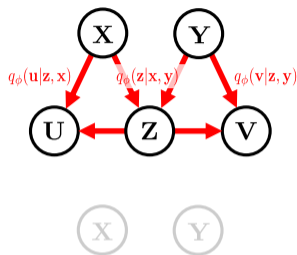
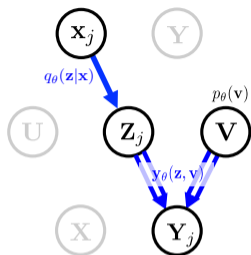
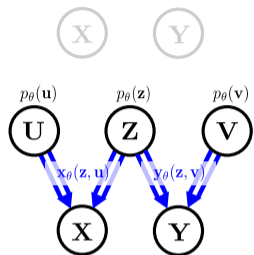
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- Priors (source of randomness): common $p_\theta(\mathbf{z})$, local $p_\theta(\mathbf{u})$, $p_\theta(\mathbf{v})$

Probabilistic model for joint and conditional sampling



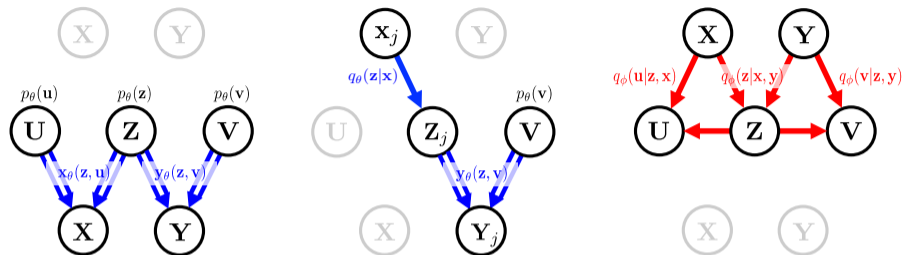
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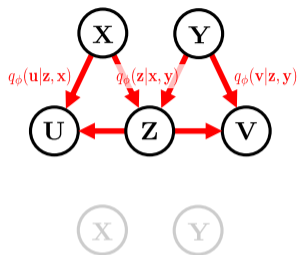
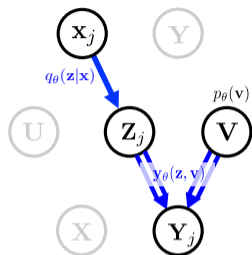
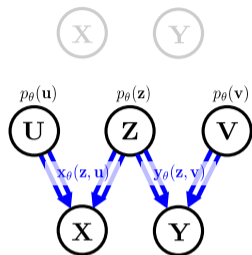
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- Variational encoders: joint $q_\phi(z|x, y)$, local $q_\phi(u|z, x)$, $q_\phi(v|z, y)$

Probabilistic model for joint and conditional sampling



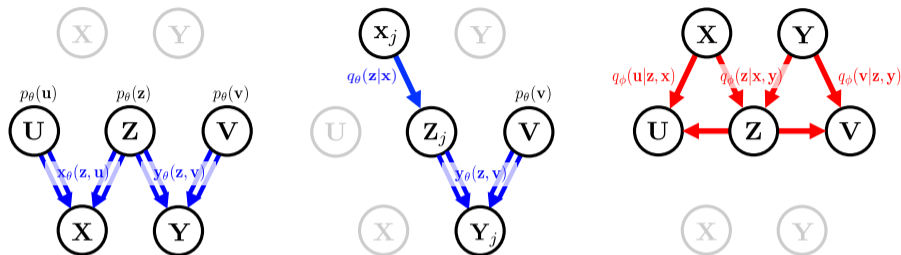
- Decoders: $\mathbf{x}_\theta(\mathbf{z}, \mathbf{u})$, $\mathbf{y}_\theta(\mathbf{z}, \mathbf{v})$
- Priors (source of randomness): common $p_\theta(\mathbf{z})$, local $p_\theta(\mathbf{u})$, $p_\theta(\mathbf{v})$
- Model (marginal) encoders: $q_\theta(\mathbf{z}|\mathbf{x})$, $q_\theta(\mathbf{z}|\mathbf{y})$
- Variational encoders: joint $q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y})$, local $q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x})$, $q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y})$
- Call these components in entirety the **variational Wyner model**

Probabilistic model for joint and conditional sampling



- Decoders: $\mathbf{x}_\theta(\mathbf{z}, \mathbf{u}), \mathbf{y}_\theta(\mathbf{z}, \mathbf{v})$
 - Priors (source of randomness): common $p_\theta(\mathbf{z})$, local $p_\theta(\mathbf{u}), p_\theta(\mathbf{v})$
 - Model (marginal) encoders: $q_\theta(\mathbf{z}|\mathbf{x}), q_\theta(\mathbf{z}|\mathbf{y})$
 - Variational encoders: joint $q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y})$, local $q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y})$
 - Call these components in entirety the **variational Wyner model**
- } model θ
 } variational ϕ

Probabilistic model for joint and conditional sampling



- Decoders: $x_\theta(z, u)$, $y_\theta(z, v)$ } decoders p
- Priors (source of randomness): common $p_\theta(z)$, local $p_\theta(u)$, $p_\theta(v)$ }
- Model (marginal) encoders: $q_\theta(z|x)$, $q_\theta(z|y)$ } encoders q
- Variational encoders: joint $q_\phi(z|x, y)$, local $q_\phi(u|z, x)$, $q_\phi(v|z, y)$ }
- Call these components in entirety the **variational Wyner model**

Training objectives

- The variational Wyner model induces four distributions:

joint

cond. ($x \rightarrow y$)

cond. ($y \rightarrow x$)

variational

Training objectives

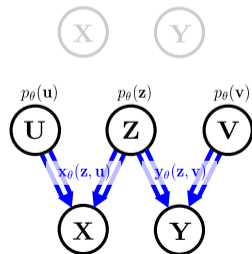
- The variational Wyner model induces four distributions:

joint $p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$

cond. ($x \rightarrow y$)

cond. ($y \rightarrow x$)

variational

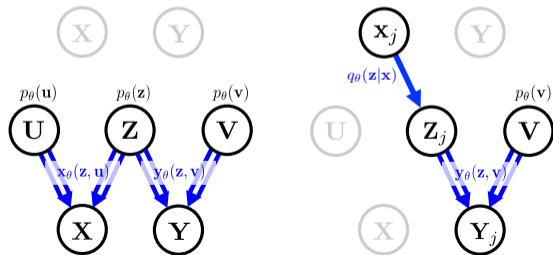


Training objectives

- The variational Wyner model induces four distributions:

joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
cond. ($x \rightarrow y$)	$p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q_{\theta}(\mathbf{z} \mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
cond. ($y \rightarrow x$)	

variational

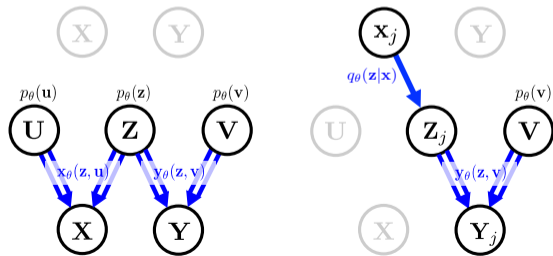


Training objectives

- The variational Wyner model induces four distributions:

joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
cond. ($x \rightarrow y$)	$p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_{\theta}(\mathbf{z} \mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
cond. ($y \rightarrow x$)	$p_{y \rightarrow x}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_{\theta}(\mathbf{z} \mathbf{y})p_{\theta}(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))$

variational



Training objectives

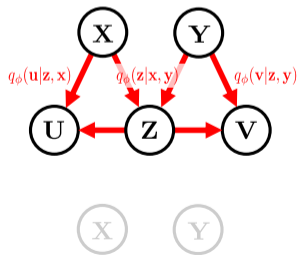
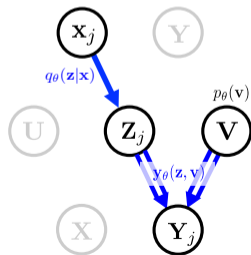
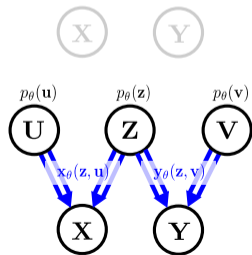
- The variational Wyner model induces four distributions:

joint $p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$

cond. ($x \rightarrow y$) $p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_{\theta}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$

cond. ($y \rightarrow x$) $p_{y \rightarrow x}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_{\theta}(\mathbf{z}|\mathbf{y})p_{\theta}(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))$

variational $q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x})q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y})$



Training objectives

- The variational Wyner model induces four distributions:

joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
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cond. ($x \rightarrow y$)	$p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_{\theta}(\mathbf{z} \mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$
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cond. ($y \rightarrow x$)	$p_{y \rightarrow x}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_{\theta}(\mathbf{z} \mathbf{y})p_{\theta}(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))$
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variational	$q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{u} \mathbf{z}, \mathbf{x})q_{\phi}(\mathbf{v} \mathbf{z}, \mathbf{y})$
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- Recall Wyner's optimization problem:

minimize	$I(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$\mathbf{X} - \mathbf{Z} - \mathbf{Y}$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y})$

Training objectives

- The variational Wyner model induces four distributions:

$$\text{joint} \quad p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$$

$$\text{cond. } (\mathbf{x} \rightarrow \mathbf{y}) \quad p_{\mathbf{x} \rightarrow \mathbf{y}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_{\theta}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$$

$$\text{cond. } (\mathbf{y} \rightarrow \mathbf{x}) \quad p_{\mathbf{y} \rightarrow \mathbf{x}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_{\theta}(\mathbf{z}|\mathbf{y})p_{\theta}(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))$$

$$\text{variational} \quad q_{\mathbf{xy} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x})q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y})$$

- Recall Wyner's optimization problem:

$$\begin{array}{ll} \text{minimize} & I(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & \mathbf{X} - \mathbf{Z} - \mathbf{Y} \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}) \end{array}$$

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$, we can relax the problem as

$$\text{minimize} \quad D(p_{\text{model}}, q_{\mathbf{xy} \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

Training objectives

- The variational Wyner model induces four distributions:

$$\text{joint} \quad p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_{\theta}(\mathbf{z})p_{\theta}(\mathbf{u})p_{\theta}(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$$

$$\text{cond. } (\mathbf{x} \rightarrow \mathbf{y}) \quad p_{\mathbf{x} \rightarrow \mathbf{y}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_{\theta}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_{\theta}(\mathbf{z}, \mathbf{v}))$$

$$\text{cond. } (\mathbf{y} \rightarrow \mathbf{x}) \quad p_{\mathbf{y} \rightarrow \mathbf{x}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_{\theta}(\mathbf{z}|\mathbf{y})p_{\theta}(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_{\theta}(\mathbf{z}, \mathbf{u}))$$

$$\text{variational} \quad q_{\mathbf{xy} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y})q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x})q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y})$$

- Recall Wyner's optimization problem:

minimize	$I(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$\mathbf{X} - \mathbf{Z} - \mathbf{Y}$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y})$

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$, we can relax the problem as

minimize	$D(p_{\text{model}}, q_{\mathbf{xy} \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
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- Distribution matching with CI regularization

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

minimize	$I_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$\mathbf{X} - \mathbf{Z} - \mathbf{Y}$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y})$

Derivation

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

minimize	$I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$\mathbf{X} - \mathbf{Z} - \mathbf{Y}$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y})$

- ① Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

minimize	$I_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \equiv q_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u} \mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v} \mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

- ① Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency

Derivation

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{array}{ll} \text{minimize} & I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0 \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- ① Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

$$\begin{array}{ll} \text{minimize} & I_{\mathbf{xy} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{\mathbf{xy} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0 \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- 1 Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- 2 Replace $I_{\mathbf{xy} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

$$\begin{array}{ll} \text{minimize} & I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0 \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- ① Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- ② Replace $I_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

minimize	$I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0$
variables	$q_{\phi}(\mathbf{z} \mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u} \mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v} \mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

- 1 Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- 2 Replace $I_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
- 3 Relax the equality constraint

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

$$\begin{array}{ll} \text{minimize} & I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) \leq \epsilon \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- 1 Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- 2 Replace $I_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
- 3 Relax the equality constraint

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{array}{ll} \text{minimize} & I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) \leq \epsilon \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- 1 Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- 2 Replace $I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
- 3 Relax the equality constraint
- 4 Convert to an unconstrained Lagrangian minimization

Derivation

- For each model $p_{\text{model}} \in \{p_{\mathbf{x} \rightarrow \mathbf{y}}, p_{\mathbf{x} \rightarrow \mathbf{z}}, p_{\mathbf{y} \rightarrow \mathbf{x}}\}$:

$$\begin{array}{ll} \text{minimize} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{\mathbf{x}\mathbf{y} \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & \\ \text{variables} & q_{\phi}(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

- 1 Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
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- 3 Relax the equality constraint
- 4 Convert to an unconstrained Lagrangian minimization

Training method

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}, p_{xy \rightarrow}\}$,

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- Distribution matching with CI regularization

Training method

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}, p_{xy \rightarrow}\}$,

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- **Distribution matching** with **CI regularization**
- **Simultaneous training**: minimize a weighted sum of the objectives

Training method

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}, p_{xy \rightarrow}\}$,

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- **Distribution matching** with **CI regularization**
- **Simultaneous training**: minimize a weighted sum of the objectives
- **Symmetric KL divergence** $D_{\text{sym}}(p, q) \triangleq D_{\text{KL}}(p \parallel q) + D_{\text{KL}}(q \parallel p)$

Training method

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}, p_{y \rightarrow x}\}$,

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- **Distribution matching** with **CI regularization**
- **Simultaneous training**: minimize a weighted sum of the objectives
- **Symmetric KL divergence** $D_{\text{sym}}(p, q) \triangleq D_{\text{KL}}(p \parallel q) + D_{\text{KL}}(q \parallel p)$
- **Variational density-ratio estimation technique** [Pu+17]: a variant of the discriminator trick of generative adversarial networks (GANs)

Training method

- For each model $p_{\text{model}} \in \{p_{x \rightarrow y}, p_{y \rightarrow x}, p_{y \rightarrow x}\}$,

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- **Distribution matching** with **CI regularization**
- **Simultaneous training**: minimize a weighted sum of the objectives
- **Symmetric KL divergence** $D_{\text{sym}}(p, q) \triangleq D_{\text{KL}}(p \parallel q) + D_{\text{KL}}(q \parallel p)$
- **Variational density-ratio estimation technique** [Pu+17]: a variant of the discriminator trick of generative adversarial networks (GANs)
- In practice, $\lambda_{\text{model}}^{\text{CI}}$ can be chosen by **trial-and-errors**

Training with variational density-ratio estimation technique

- A variant of the **discriminator trick** of **generative adversarial networks** [Pu+17]

Training with variational density-ratio estimation technique

- A variant of the **discriminator trick** of **generative adversarial networks** [Pu+17]
- Suppose we wish to solve

$$\min_{\theta} D_{\text{KL}}(p_{\theta}(s) \parallel q_{\theta}(s)) = \mathbb{E}_{p_{\theta}(s)} \left[\log \frac{p_{\theta}(s)}{q_{\theta}(s)} \right]$$

with no explicit density models on $p_{\theta}(s)$ and $q_{\theta}(s)$

Training with variational density-ratio estimation technique

- A variant of the **discriminator trick** of **generative adversarial networks** [Pu+17]
- Suppose we wish to solve

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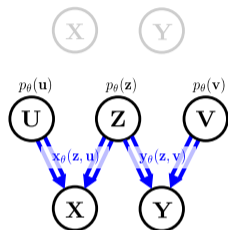
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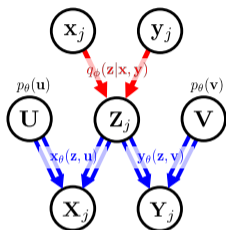
- **Plug in and optimize:**

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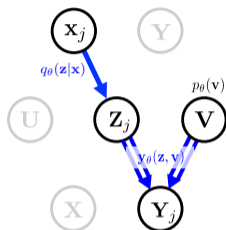
How to use the variational Wyner model



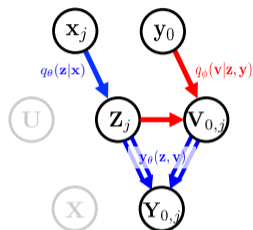
(a) Joint sampling



(b) Joint stochastic reconstruction



(c) Conditional sampling



(d) Conditional sampling with style control

- Variational encoders are introduced for training, but can be also used in sampling
- Local variational encoders $q_\phi(u|z, x)$, $q_\phi(v|z, y)$ can be viewed as style extractors

Experiment. MNIST–SVHN add-1 dataset

- $(\mathbf{X}, \mathbf{Y}) = (\text{MNIST}, \text{SVHN})$ with $\text{label}(\text{SVHN}) = \text{label}(\text{MNIST}) + 1$

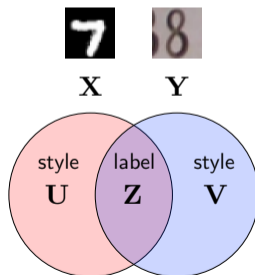


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- $\mathbf{Z} = \text{label}$, $(\mathbf{U}, \mathbf{V}) \approx (\text{style of MNIST}, \text{style of SVHN})$

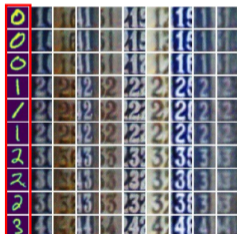


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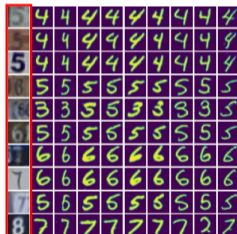
- **Generated samples:** same labels across the rows; same styles across the columns
- A **red box** highlights inputs; a **yellow box** highlight style references



(a) \rightarrow (MNIST,SVHN)



(b) MNIST \rightarrow SVHN



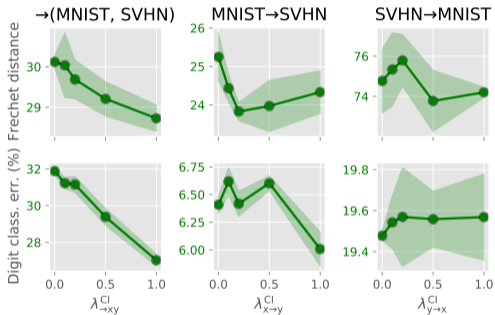
(c) SVHN \rightarrow MNIST



(d) MNIST \rightarrow SVHN
with style transfer

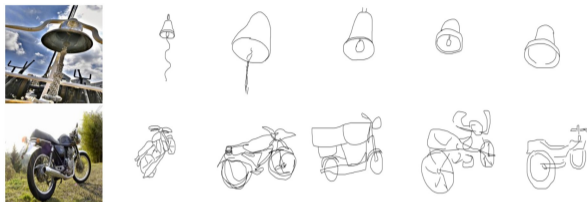
Experiment. MNIST–SVHN add-1 dataset

- Numerical evaluation: $\lambda_{\text{model}}^{\text{CI}}$ vs. quality of generated samples



Experiment. Sketchy dataset [San+16]

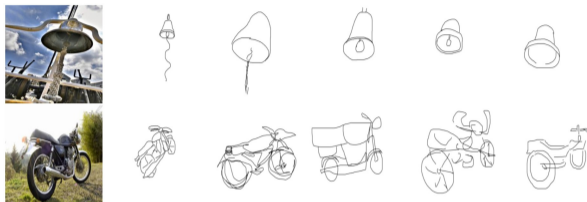
- $(\mathbf{X}, \mathbf{Y}) = (\text{photo}, \text{human sketch})$



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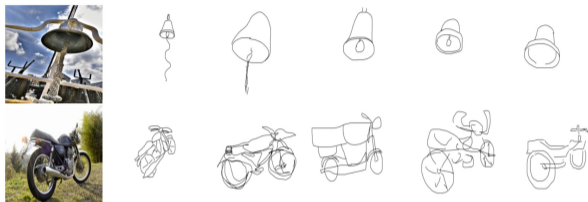
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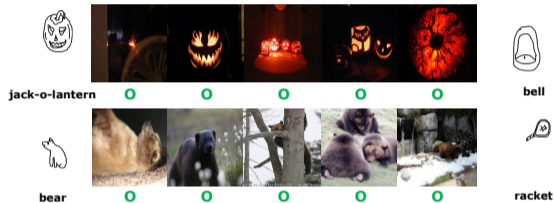
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- Our method: **retrieve via common representations**

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- **Examples:** correct (left)/wrong (right) retrievals



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- **Numerical evaluation:** precision@K (P@K), mean average precision (mAP)

Models	P@100	mAP
LCALE [Lin+20]	0.583	0.476
IIAE [Hwa+20]	0.659	0.573
Variational Wyner	0.703	0.629

Experiment. CUB image-caption

- $(\mathbf{X}, \mathbf{Y}) = (\text{bird images}, \text{captions})$



the bird has a white body,
black wings, and webbed
orange feet



a blue bird with gray
primaries and secondaries
and white breast and throat




- Used ResNet-101 features for images

Experiment. CUB image-caption























→(image, caption)

			
this small bird is black white white with a small bill and black feet	this bird is grey with grey and a black beak , pointy short pointy beak .	this is a black and white black bird and a short black beak .	this bird has a black and and white and white feathers and
			
this white bird is mostly white white with a long bill , and black feet	this bird is grey with grey and has long long, pointy short pointy beak	this is a black and white black bird and a long long yellow . .	this bird has a white and and white and white with and feet .

image→caption

input image from test set	generated captions		
	this bird has a black crown and breast , with a crown , and and and black red its . .	this is a very , and white and and color with with a , and and a long blue patches . .	this bird has a very , thin beak with a breast and a brown beak , the body rimmed body .
	this bird has a black crown and breast , with yellow breast and and and its of its feathers .	this bird a small , and yellow black color with with crown black black and black of its crown .	this bird has yellow small , black beak and a breast and a black feathers . the bird it's the body . .
	this bird has a red crown and breast , with red red red and red and on red its . .	this bird is a red red , red red color with with crown red and and and black red red .	the bird has red red red red , and red red and a red beak . the red 's feathers .

caption→image

input text from test set	ground truth	retrievals from generated features										
This bird has yellow topped black and white striped wings and some red markings on its belly.												
This bird has wings that are gray and has a white belly.												

Experiment. CUB image-caption

- **Numerical evaluation:** correlation of generated samples

Model	joint	image→caption	caption→image
Test set		0.273	
MMVAE [Shi+19]	0.263	0.104	0.135
Variational Wyner	0.303	0.327	0.318

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“Learning with Succinct Common Representation with Wyner's Common Information”, **J. Jon Ryu**, Yoojin Choi, Young-Han Kim, Mostafa El-Khamy, and Jungwon Lee, arXiv:1905.10945, Under Review

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